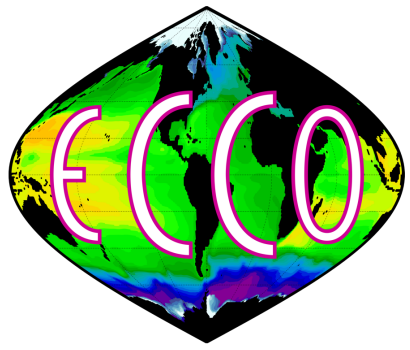


ECCO Modeling Utilities (EMU)

A set of menu-driven tools
for analyzing the ECCO model.

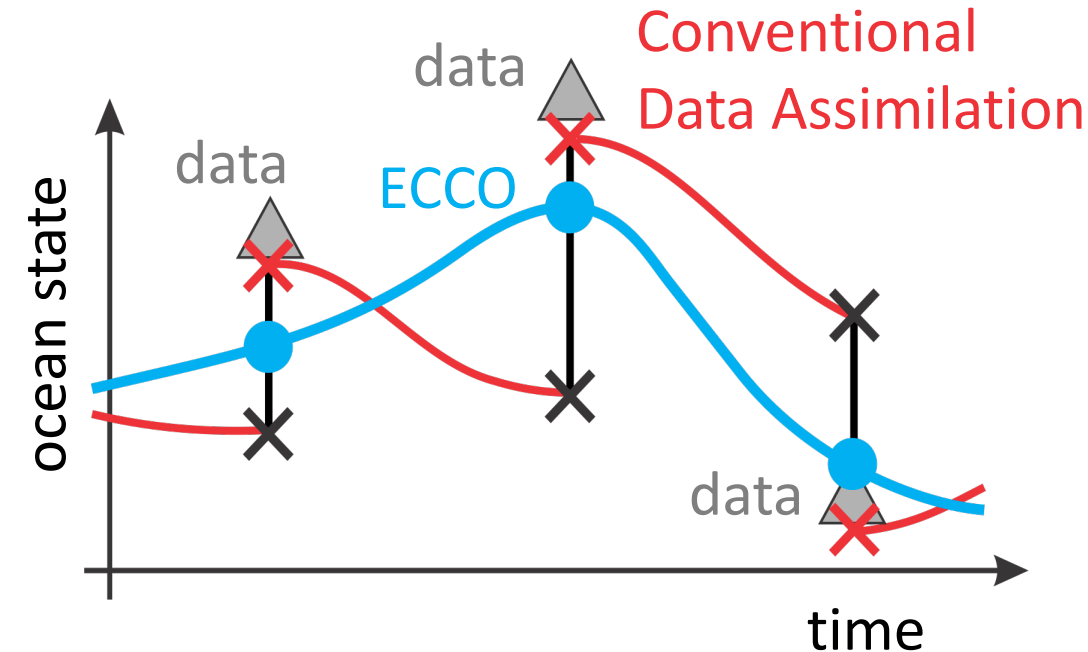
Ichiro Fukumori, Ou Wang, Ian Fenty
Jet Propulsion Laboratory, California Institute of Technology

20 March 2024, ECCO Meeting, Austin TX

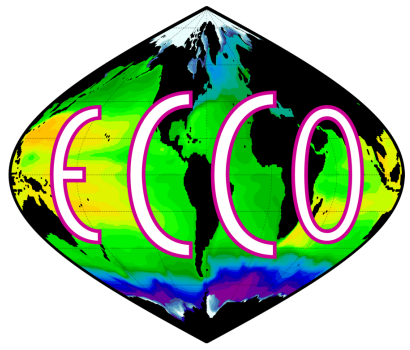


ECCO Modeling Utilities (EMU)

Why? A set of menu-driven tools for analyzing the ECCO model.

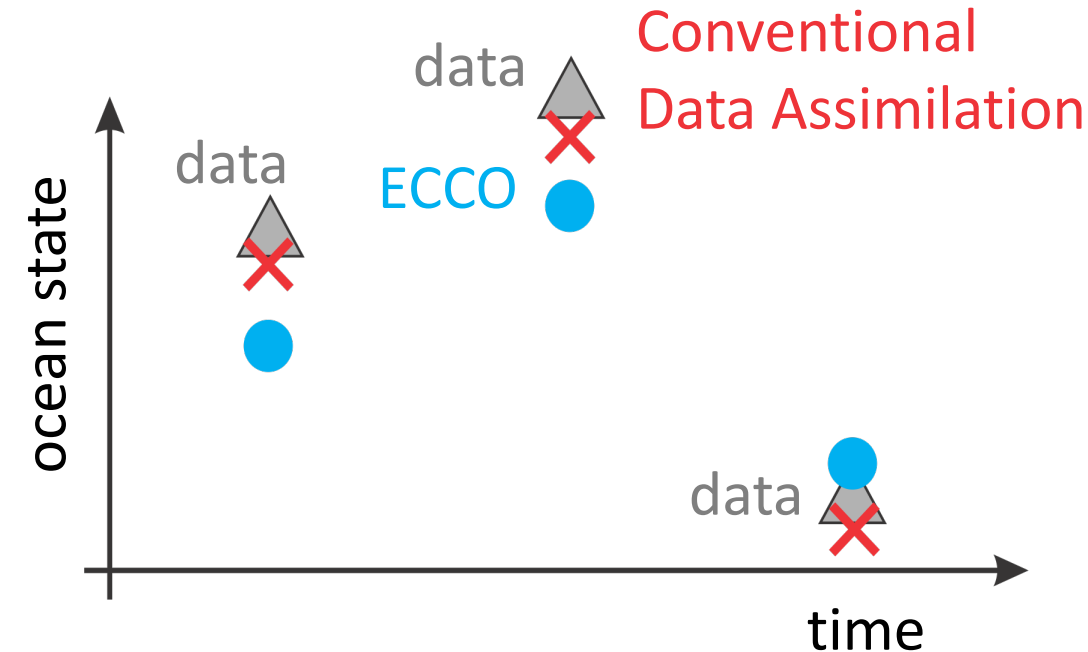


- 1) ECCO is a state-of-the-art synthesis of ocean observations,
- 2) ECCO is characterized by its physical consistency (e.g., closed budgets),
- 3) The physics of this consistency is embodied in the model,
- 4) EMU permits analyses of the model's physics (e.g., causation) without needing modeling expertise.

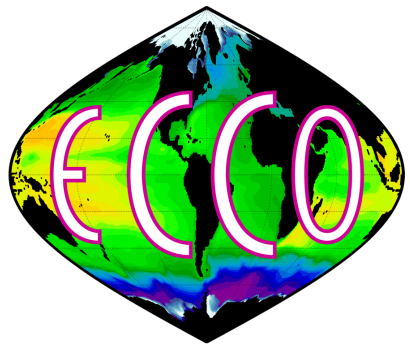


ECCO Modeling Utilities (EMU)

Why? A set of menu-driven tools for analyzing the ECCO model.



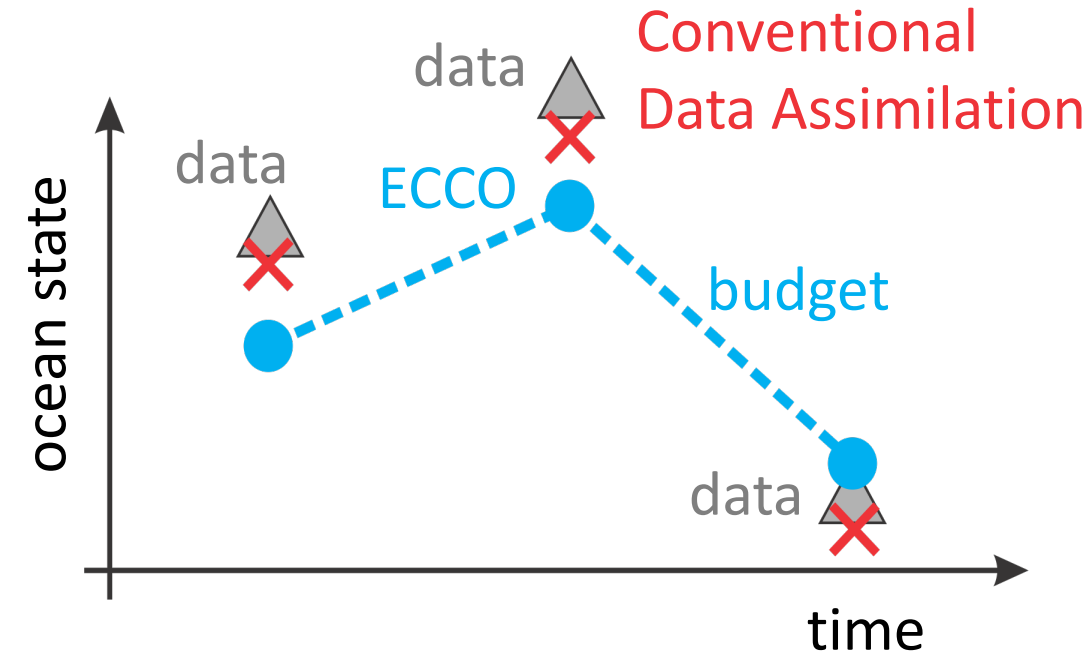
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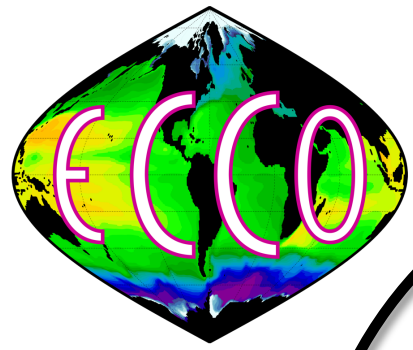
ECCO Modeling Utilities (EMU)

Why?

A set of menu-driven tools for analyzing the ECCO model.



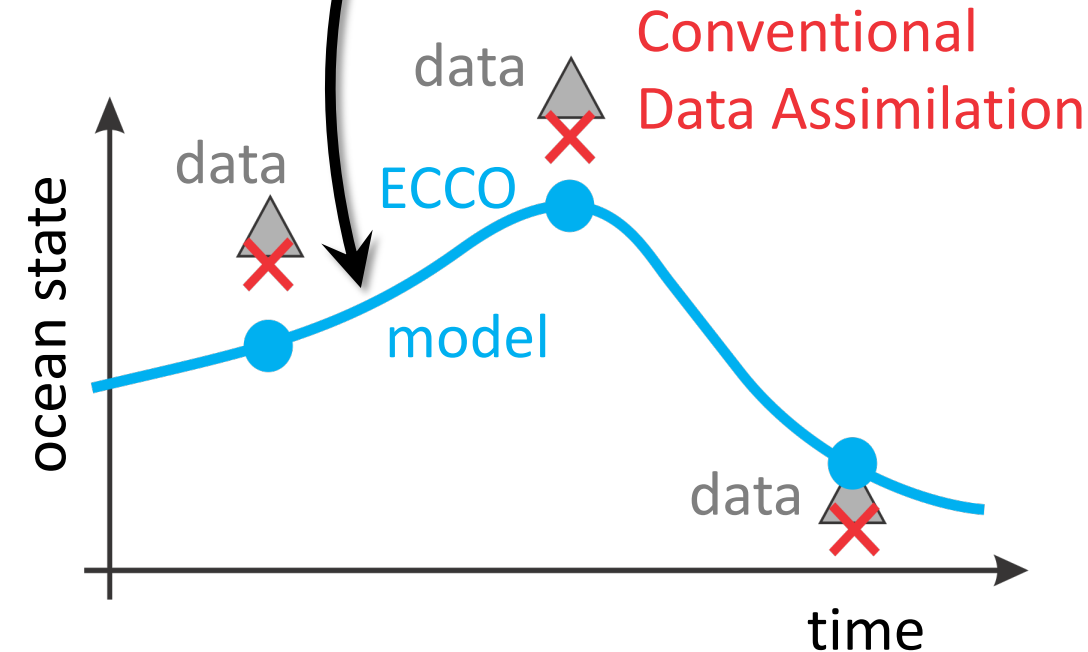
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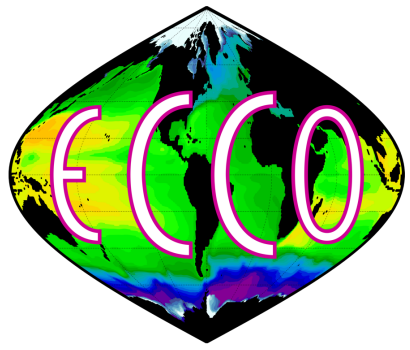
ECCO Modeling Utilities (EMU)

This is Why!

A set of menu-driven tools for analyzing the ECCO model.



- 1) ECCO is a state-of-the-art synthesis of ocean observations,
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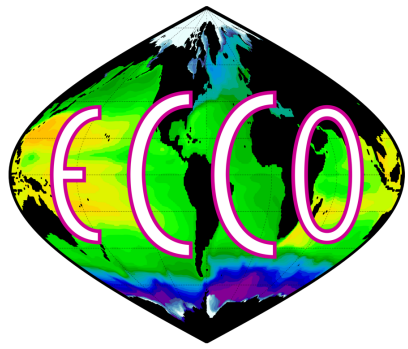


ECCO Modeling Utilities (EMU)

A set of menu-driven tools for analyzing the ECCO model.



	Tool	Description
1	Sampling	Evaluates time-series of state.
2	Forward Gradient	Computes model's response to change in forcing.
3	Adjoint	Computes model's sensitivity to forcing (adjoint gradient).
4	Convolution	Evaluates convolution of adjoint gradients with forcing (adjoint gradient decomposition).
5	Tracer	Computes evolution of passive tracer and its adjoint.
6	Budget	Evaluates budget time-series.
7	Modified Simulation	Reruns simulation with changes (e.g., forcing).
8	Attribution	Evaluates effects by control type.

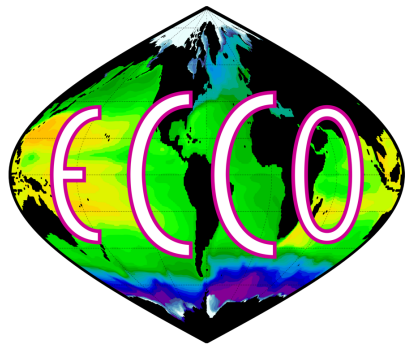


ECCO Modeling Utilities (EMU)

A set of menu-driven tools for analyzing the ECCO model.



	Tool	
1	Sampling	<ul style="list-style-type: none">✓ Evaluates any linear combination of the model state✓ Options to use latitude, longitude, depth as criteria✓ Useful for assessing fidelity of ECCO
2	Forward Gradient	Computes model's response to change in forcing.
3	Adjoint	Computes model's sensitivity to forcing (adjoint gradient).
4	Convolution	Evaluates convolution of adjoint gradients with forcing (adjoint gradient decomposition).
5	Tracer	Computes evolution of passive tracer and its adjoint.
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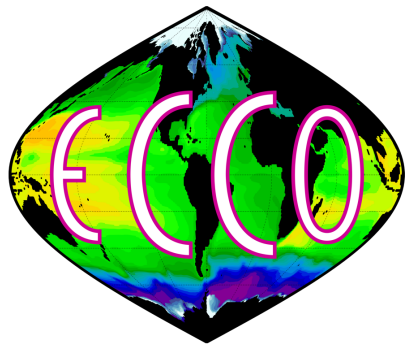


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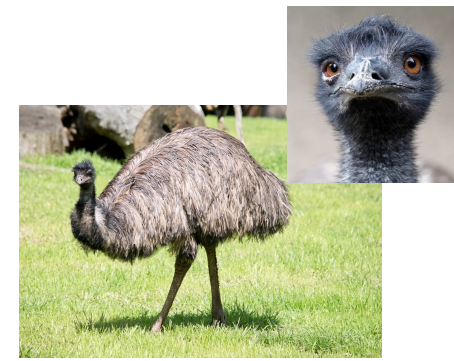


	Tool	
1	Sampling	<ul style="list-style-type: none"> ✓ Computes forward gradient ✓ Choice of denominator ✓ Useful for insight into physics ✓ Also useful for validating adjoint $\frac{\partial (\text{model state})}{\partial (\text{control})}$
2	Forward Gradient	
3	Adjoint	<ul style="list-style-type: none"> ✓ Computes adjoint gradient ✓ Choice of numerator ✓ Useful for insight into physics ✓ Also useful for model calculus $\frac{\partial (\text{model state})}{\partial (\text{control})}$
4	Convolution	
5	Tracer	Computes evolution of passive tracer and its adjoint.
6	Budget	Evaluates budget time-series.
7	Modified Simulation	Reruns simulation with changes (e.g., forcing).
8	Attribution	Evaluates effects by control type.

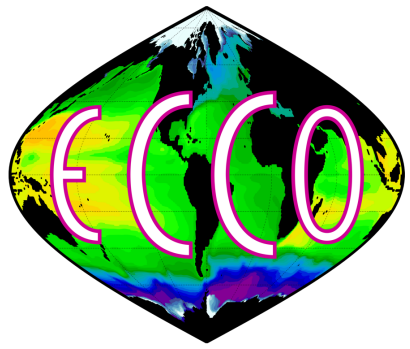


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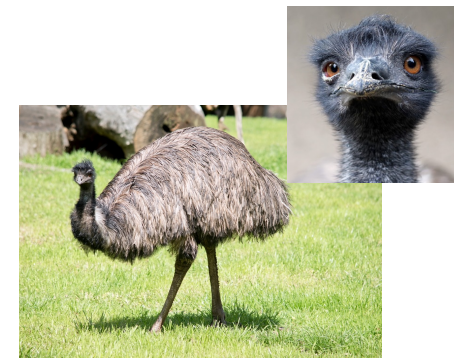


	Tool	Description
1	Sampling	Evaluates time-series of state.
2	Forward Gradient	Computes model's response to change in forcing.
3	Adjoint	<div style="border: 2px solid black; padding: 10px;"> <p>✓ Expands quantities of interest into their controls</p> $\delta J(t) \approx \sum_i \sum_r \sum_{\Delta t} \frac{\partial J(t_g)}{\partial \phi_i(\mathbf{r}, t_g - \Delta t)} \delta \phi_i(\mathbf{r}, t - \Delta t)$ <p style="text-align: right;">← adjoint gradient</p> <p>✓ Options to use modified gradients & forcing</p> <p>✓ Useful in identifying causal mechanisms</p> </div>
4	Convolution	
5	Tracer	
6	Budget	
7	Modified Simulation	Reruns simulation with changes (e.g., forcing).
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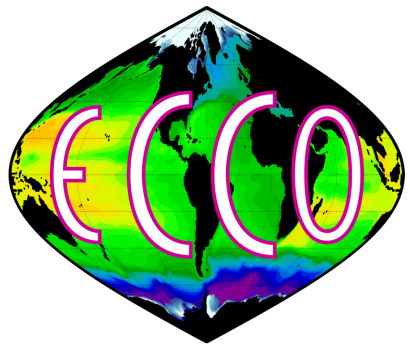


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	Tool	Description
1	Sampling	Evaluates time-series of state.
2	Forward Gradient	Computes model's response to change in forcing.
3	Adjoint	Computes model's sensitivity to forcing (adjoint gradient).
4	Convolution	Evaluates convolution of adjoint gradients with forcing
5	Tracer	<ul style="list-style-type: none">✓ Computes evolution of passive tracer and its adjoint✓ Useful in identifying origin & fate of water masses and their circulation pathways
6	Budget	Evaluates budget time-series.
7	Modified Simulation	Reruns simulation with changes (e.g., forcing).
8	Attribution	Evaluates effects by control type.

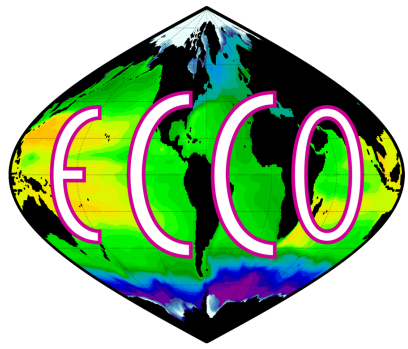


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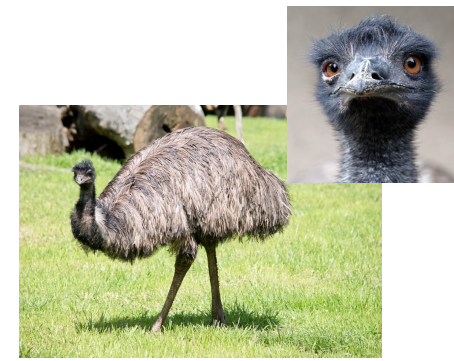


	Tool	Description
1	Sampling	Evaluates time-series of state.
2	Forward Gradient	Computes model's response to change in forcing.
3	Adjoint	Computes model's sensitivity to forcing (adjoint gradient).
4	Convolution	Evaluates convolution of adjoint gradients with forcing (adjoint gradient decomposition).
5	Tracer	Computes evolution of passive tracer and its adjoint.
6	Budget	<ul style="list-style-type: none">✓ Evaluates property budgets✓ Useful in analyzing controlling processes
7	Modified Simulation	Reruns simulation with changes (e.g., forcing).
8	Attribution	Evaluates effects by control type.

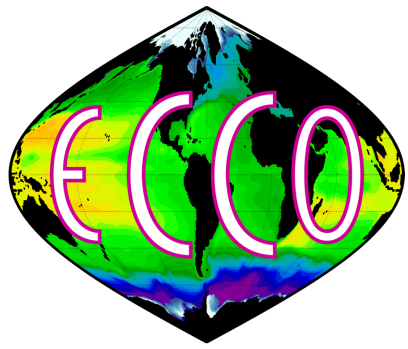


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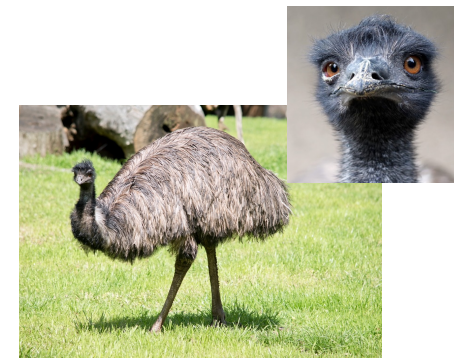


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1	Sampling	Evaluates time-series of state.
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3	Adjoint	Computes model's sensitivity to forcing (adjoint gradient).
4	Convolution	Evaluates convolution of adjoint gradients with forcing (adjoint gradient decomposition).
5	Tracer	Computes evolution of passive tracer and its adjoint.
6	Budget	Evaluates budget time-series
7	Modified Simulation	<ul style="list-style-type: none">✓ Reruns model with changes (e.g., forcing)✓ Useful in conducting experiments with the model✓ Also useful in producing non-standard output
8	Attribution	Evaluates effects by control type.



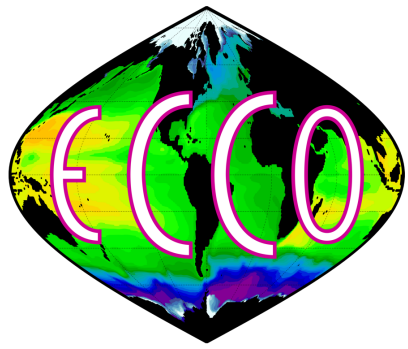
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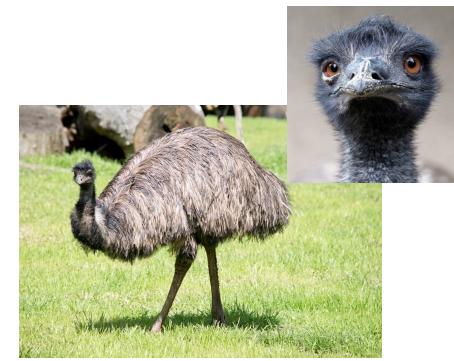
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4	Convolution	Evaluates convolution of adjoint gradients with forcing (adjoint gradient decomposition).
5	Tracer	Computes evolution of passive tracer and its adjoint.
6	Budget	✓ Evaluates model's variation by control type <i>e.g., effect of variable wind = ECCO_V4r4 – Modified_Simulation_w/o_variable_wind</i>
7	Modified Simulation	
8	Attribution	

- ✓ Useful in identifying responsible control type**
- ✓ Also useful in validating results of Convolution Tool**



ECCO Modeling Utilities (EMU)

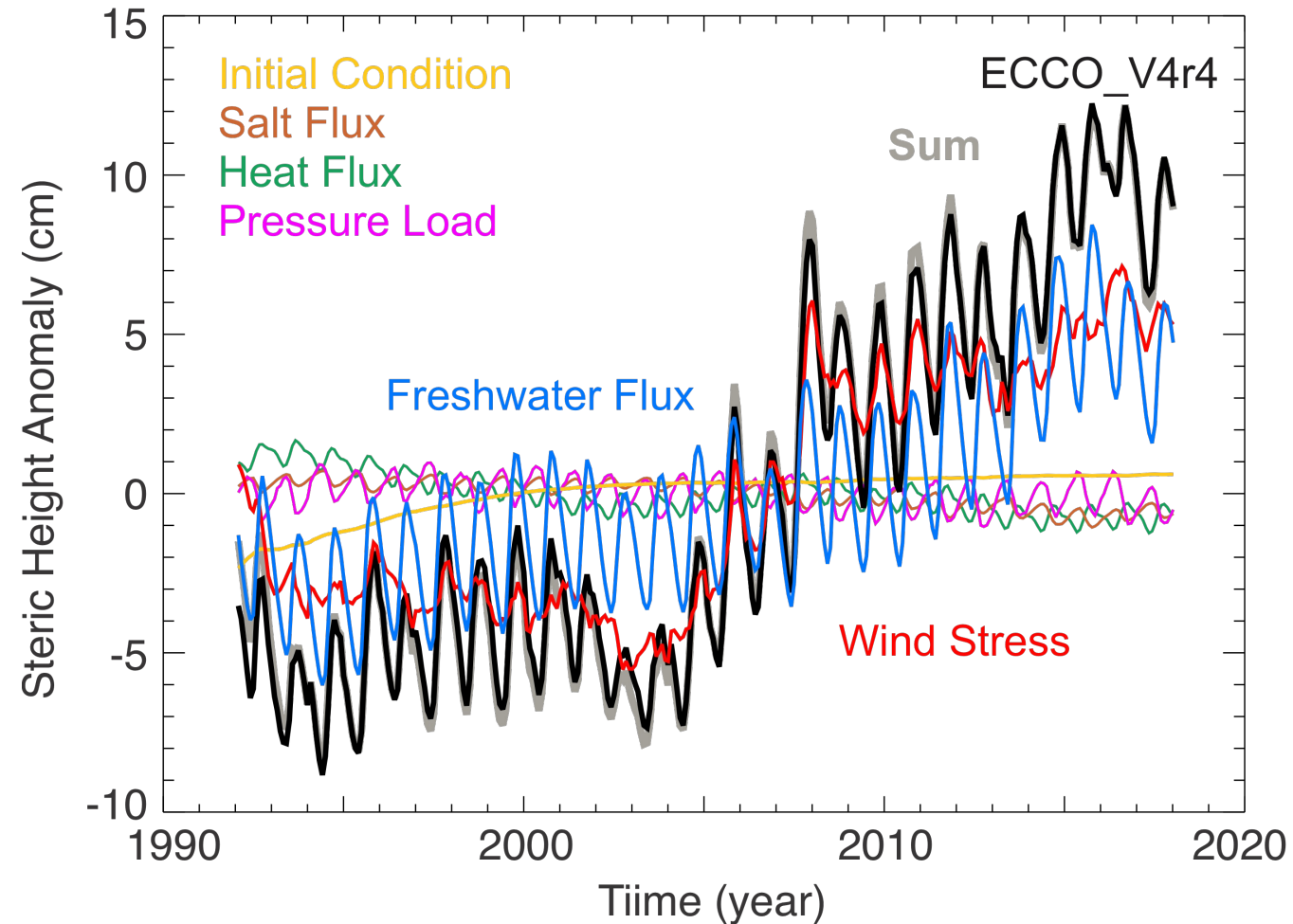
A set of menu-driven tools for analyzing the ECCO model.



	Tool	Description
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4	Convolution	
5	Tracer	
6	Budget	
7	Modified Simulation	<div style="border: 2px solid black; padding: 10px;"> <p>✓ Evaluates model's variation by control type e.g., effect of variable wind = ECCO_V4r4 – Modified_Simulation_w/o_variable_wind</p> <p>✓ Useful in identifying responsible control type</p> <p>✓ Also useful in validating results of Convolution Tool</p> </div>
8	Attribution	

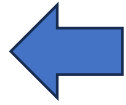
Attribution Tool Example

Beaufort Sea Mean Steric Sea Level Change



Example Running EMU (1/4)

pfe25>**emu**



EMU is launched by command "emu."

ECCO Modeling Utilities (EMU) Version 1.0a ...
See /nobackup/ifukumor/emu_v1_access/README

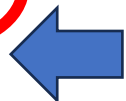
Choose among the following tools ...

- 1) Sampling (samp); Evaluates state time-series from model output.
- 2) Forward Gradient (fgrd); Computes model's forward gradient.
- 3) Adjoint (adj); Computes model's adjoint gradient.
- 4) Convolution (conv); Evaluates adjoint gradient decomposition.
- 5) Tracer (trc); Computes passive tracer evolution.
- 6) Budget (budg); Evaluates budget time-series from model output.
- 7) Modified Simulation (msim); Re-runs model with modified input.
- 8) Attribution (atrb); Evaluates state time-series by control type.

Choice of Tools

Enter choice . . (1-8)?

8



Choose Tool.

choice is 8) Attribution Tool (atrb)

Example Running EMU (2/4)

See /nobackup/ifukumor/emu_v1_access/README_atrb

README file for Attribution Tool

Define objective function (OBJF) ...

Available VARIABLES are ...

- 1) SSH (m)
- 2) OBP (equivalent sea level m)
- 3) THETA (deg C)
- 4) SALT (PSU)
- 5) UV (m/s)

OBJF

$$J(t) = \sum_i \alpha_i \sum_x \mathbf{T}_i(\mathbf{x}) v_i(\mathbf{x}, t)$$

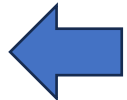
Scale Weight Variable
Multi-variable Space

Example:

Steric Sea Level = SSH – OBP
averaged over Beaufort Sea

Choose OBJF variable (v in Eq 1 of Guide) # 1 .. (1-5)?
(Enter 0 to end variable selection)

1



Choosing SSH as first variable.

OBJF variable 1 is SSH

Choose either VARIABLE at a point (1) or VARIABLE weighted in space (2) .. (1/2)?

2



Choosing a spatially weighted variable.

Example Running EMU (3/4)

Enter MASK filename (T in Eq 1 of Guide) ... ?

beaufortsea.msk

Entering filename for weight.

Enter scaling factor (alpha in Eq 1 of Guide)... ?

1.

Entering scaling factor.

Choose OBJF variable (v in Eq 1 of Guide) # 2 ... (1-5)?
(Enter 0 to end variable selection)

2

Choosing OBP as 2nd variable.

OBJF variable 2 is OBP

Choose either VARIABLE at a point (1) or VARIABLE weighted in space (2) ... (1/2)?

2

Choosing a spatially weighted variable.

Enter MASK filename (T in Eq 1 of Guide) ... ?

beaufortsea.msk

Entering filename for weight.

Enter scaling factor (alpha in Eq 1 of Guide)... ?

-1.

Entering scaling factor.

OBJF

$$J(t) = \sum_i \alpha_i \sum_{\mathbf{x}} \mathbf{T}_i(\mathbf{x}) v_i(\mathbf{x}, t)$$

Scale Weight Variable
Multi-variable Space

Example Running EMU (4/4)

Choose OBJF variable (v in Eq 1 of Guide) # 3 ... (1-5)?
(Enter 0 to end variable selection)

0 ← **Entering 0 to end OBJF specification.**

Done interactive specification.
Begin extracting time-series ...

Done. Results are in emu_atrb_m_1_beaufortsea.msk_2/output

Location of results.

pfe25> **ls -l emu_atrb_m_1_beaufortsea.msk_2/output/**

Listing results.

```
total 72
-rw-r--r-- 1 ifukumor s2904 8764 Mar 16 19:33 atrb.out_312
-rw-r--r-- 1 ifukumor s2904 1248 Mar 16 19:33 atrb.step_312
-rw-r--r-- 1 ifukumor s2904 48202 Mar 16 19:33 atrb.txt
-rw-r--r-- 1 ifukumor s2904 544 Mar 16 19:32 data.ecco
-rw-r--r-- 1 ifukumor s2904 949 Mar 16 19:32 set_samp.info
```

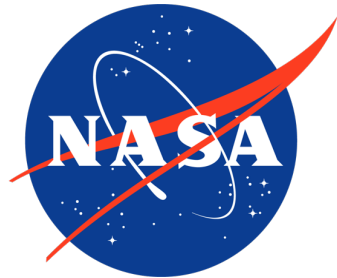
Summary & Outlook

1. EMU is available at NAS

`/nobackup/ifukumor/emu_v1_access/emu`

2. Ongoing work

- a) Containerization with Singularity & Docker
- b) Visualization (e.g., Jupyter, Python, Matlab, IDL)
- c) Updating Github repository
- d) Cloud implementation
- e) Enhancements (e.g., masks, budget)



Jet Propulsion Laboratory

California Institute of Technology

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